

	L #	Hits	Search Text	DBs	Time Stamp
1	L1	87755	(rotation\$4 adj position\$4 adj optim\$7) RPO ((access\$3 latenc\$3) near5 (optim\$11 maxim\$7 minim\$7 reduc\$7 improv\$3 decreas\$3 shrink\$3))	US-PGPUB; USPAT; EPO; JPO; IBM_TDB	2005/06/14 18:01
2	L2	17552	(vcm\$1 (voice adj coil) actuator\$1 HSA ((head\$1 arm\$1 transducer\$1) near4 (positioner\$1 motor\$1))) same ((velocit\$3 speed\$1 rate\$1 perform\$5 capab\$5 time\$1 response) near10 (current\$1 command\$2))	US-PGPUB; USPAT; EPO; JPO; IBM_TDB	2005/06/14 18:11
3	L3	278914	(seek\$3 access\$3 latenc\$3 velocit\$3 speed\$1 rate\$1 perform\$5 capab\$5 time\$1 response) near6 (estimat\$4 predict\$4 model\$4 simulat\$4)	US-PGPUB; USPAT; EPO; JPO; IBM_TDB	2005/06/14 17:56
4	L4	253	1 and 2 and 3	US-PGPUB; USPAT; EPO; JPO; IBM_TDB	2005/06/14 17:57
5	L5	112563	(rotation\$4 adj position\$4 adj optim\$7) RPO latenc\$3 (access\$3 near5 (optim\$11 maxim\$7 minim\$7 reduc\$7 improv\$3 decreas\$3 shrink\$3))	US-PGPUB; USPAT; EPO; JPO; IBM_TDB	2005/06/14 18:02
6	L6	331	2 and 3 and 5	US-PGPUB; USPAT; EPO; JPO; IBM_TDB	2005/06/14 18:06
7	L7	1061	(vcm\$1 (voice adj coil) actuator\$1 HSA ((head\$1 arm\$1 transducer\$1) near4 (positioner\$1 motor\$1))) and ((velocit\$3 speed\$1 rate\$1 perform\$5 capab\$5 time\$1 response) near6 (current\$1 command\$2)) and 3 and 5	US-PGPUB; USPAT; EPO; JPO; IBM_TDB	2005/06/14 18:13
8	L8	190	7 and (360/78.04.ccls. 360/78.06-78.09.ccls. 360/78.12.ccls. 360/78.14.ccls. 710/5-6.ccls. 710/39-40.ccls. 710/310.ccls. 711/111-113.ccls. 711/137.ccls. 711/151.ccls. 711/158.ccls. 711/167.ccls.)	US-PGPUB; USPAT; EPO; JPO; IBM_TDB	2005/06/14 18:13
9	L9	146	(6 8) not 4	US-PGPUB; USPAT; EPO; JPO; IBM_TDB	2005/06/14 18:14